

# TWISTER<sup>2</sup> – Tube Bending System for the Production of Two- and three-dimensional Parts made of Tube and Solid Material



TWISTER<sup>2</sup>  
12-RL  
18-RL  
20-R  
25-RL  
35-RL

# TWISTER<sup>2</sup>

12-RL

18-RL

20-R

25-RL

35-RL

▼ TWISTER<sup>2</sup> 20-R



▼ Bending tool TWISTER<sup>2</sup> 18-RL



## Our Accomplishments for Your Benefit

- TWISTER<sup>2</sup> speaks EasyWay - the control platform for robot and machine
- Unique, fully integrated system
- Process reliability and productivity leap for a flexible production of three-dimensional geometries
- Intelligent combination of handling and bending tasks thanks to collaboration between robot and bending unit
- Modular design enables incorporation of external systems and subsequent processes
- Freely selectable bending sequence of geometry elements

## Control System

- Reliable WPS 3.2 EasyWay control concept
- Interactive graphical 3D programming of tubes, transfer of drawing dimensions
- Fully integrated robot concept with cross-system programming that requires no robot knowledge
- *iQtube* for graphically simulating the bending sequence, with integrated collision monitoring and theoretical output calculation
- Joint transformation of all machine and robot axes

## Design Features

- Optional rotary gripper for complete rotation of the workpiece in one clamping and freely programmable regrabbing function for every gripper position. The Twister<sup>2</sup> 35 RL also allows the bending of different tube diameters without any tool changes.
- The Power Gripper enables shortest clamping lengths with highest gripping force
- Different bending heads for rotary-draw bending and a modular system enable customized machine configurations
- Short set-up times due to sophisticated tool solutions

▼ Bending head TWISTER<sup>2</sup> 12-RL



# Precise, Reliable, Versatile and Profitable – WAFIOS TWISTER<sup>2</sup>

## Perfect Union of Design and Functionality

A modular concept combines robot and bending technology at the highest level. The fully integrated robot control guarantees a simple programming process while maximum flexibility and integrated automation is ensured.

The newly developed bending system meets highest demands with respect to:

- Output and bending quality
- Greater range of parts thanks to extremely high degrees of freedom.
- Automation and linking of applications / process steps
- Maintenance, service and user friendliness

The unique modular system meets demands flexibly and ideally and enables an integration of different tasks in one fully automatic machinery system. The integration of customer-side processes or the combination of multiple TWISTER<sup>2</sup> machines is possible. (Example: Twister<sup>2</sup> TWINS)

## Quality

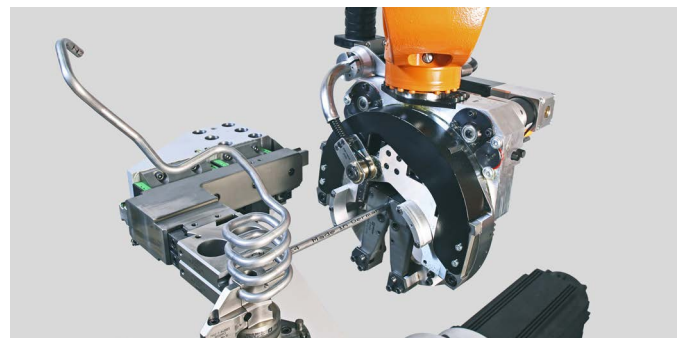
Since 1893, the WAFIOS name is synonymous with outstanding quality, safety standards, and technical innovations in the German mechanical engineering industry.

## Reliability

Strict quality controls, state-of-the-art production systems, and many years of experience guarantee that your investment is safe in our hands. Our global service network ensures high availability of WAFIOS machinery.

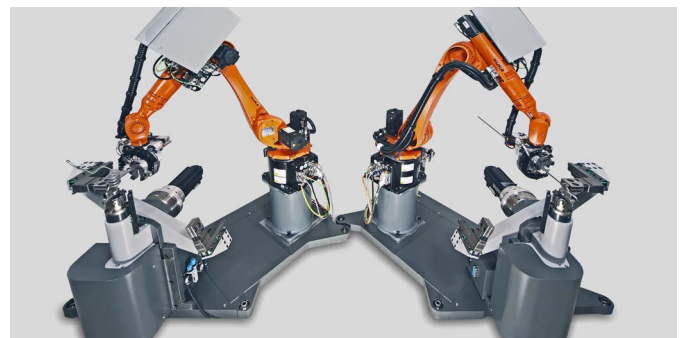
## Cost efficiency

High production output and a long service life will save money and shorten the amortization time of your investment.



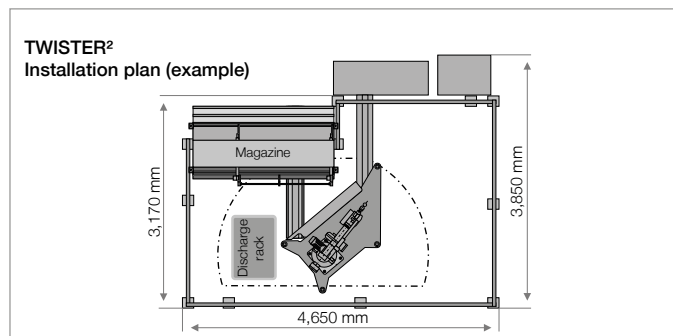
▲ Rotary gripper with bending head

▼ TWISTER<sup>2</sup> TWINS



▲ Power Gripper

Technical Data	TWISTER <sup>2</sup> 12-RL	TWISTER <sup>2</sup> 18-RL	TWISTER <sup>2</sup> 20-R	TWISTER <sup>2</sup> 25-RL	TWISTER <sup>2</sup> 35-RL
<b>Work area</b> Max. tube diameter Nominal bending moment according to (VDI 3421) Standard length from magazine	12.7 mm 74 Nm 2,000 mm (3,000 mm option)	18.0 mm 220 Nm 2,000 mm (3,000 mm option)	20.0 mm 360 Nm 2,000 mm (3,000 mm option)	25.4 mm 510 Nm 2,000 mm (4,000 mm option)	1-35 mm 1.200 Nm 2.000 mm (4.000 mm Option)
<b>CNC axes</b> Machine axes completely integrated into robot axes Bending head	4 3	4 3 + 1 servomotor-driven vertical clamping function (option) + 1 servomotor-driven pressure die + 1 servomotor-driven tube support (option)	4 3 + 1 servomotor-driven tube support + 1 servomotor-driven pressure die	4 5 + 1 Positioning unit	4 5 + 1 Positioning unit
<b>Tube grippers</b> Rotary Gripper Power Gripper Operating principle	Yes Yes Pneumatic	Yes Yes Pneumatic	No Yes Pneumatic	No Yes Pneumatic	Yes Yes Pneumatic
<b>Programming</b> Control of robot by Machine axes Length/angle Coordinates Job order lists Simulation	Yes Yes Yes Yes Option	Yes Yes Yes Yes Option	Yes Yes Yes Yes Option	Yes Yes Yes Yes Option	Yes Yes Yes Yes Option
<b>Machine control</b>	WPS 3.2 EasyWay	WPS 3.2 EasyWay	WPS 3.2 EasyWay	WPS 3.2 EasyWay	WPS 3.2 EasyWay
<b>Automation</b> Loading from a magazine Position-oriented discharge	Option Yes	Option Yes	Option Yes	Option Yes	Option Yes
<b>Linking of other processes</b>	Yes	Yes	Yes	Yes	Yes



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